### Week 1: Basics & Implementation

**Topics:** - Input/Output, Loops, Conditionals - Arrays, Strings, Basic Math - Simple sorting

**Weekly Tips:** - Focus on writing clean, readable code. - Always test edge cases (0, 1, negative numbers, large numbers). - Use online judge IDE or local compiler to verify behavior.

### Week 2: Ad-hoc & Simulation

**Topics:** - Simulation - Ad-hoc logic problems - Greedy basics

**Weekly Tips:** - Think step by step, simulate processes on paper first. - Carefully read problem constraints to optimize loops. - Greedy approach works if problem guarantees local optimality leads to global optimality.

### Week 3: Sorting & Searching

**Topics:** - Sorting algorithms: QuickSort, MergeSort, STL sort - Binary Search & Ternary Search - Two-pointer technique

**Weekly Tips:** - Always check if STL sort suffices before implementing manually. - Binary search can be applied to sorted arrays or answer space. - Two-pointer technique is useful for finding pairs, sums, or sliding windows.

### Week 4: Strings & Pattern Matching

**Topics:** - String searching: KMP, Rabin-Karp - Palindromes & substrings - Prefix/Suffix techniques

**Weekly Tips:** - Understand failure function in KMP for linear-time matching. - Use rolling hash for fast substring comparison. - Practice manipulating strings efficiently with STL.

### Week 5: Recursion & Backtracking

**Topics:** - Recursion basics - Backtracking: N-Queens, subsets, combinations - Depth-First Search (DFS) for combinatorial problems

**Weekly Tips:** - Draw recursion trees to understand problem flow. - Watch stack usage and avoid unnecessary deep recursion. - Memoization can be applied to optimize repetitive recursive calls.

### Week 6: Graph Theory Basics

**Topics:** - Graph representation: adjacency list & matrix - BFS & DFS traversal - Connected components - Shortest paths (Dijkstra, BFS for unweighted)

**Weekly Tips:** - Always check graph type: directed, undirected, weighted, unweighted. - Use visited array to avoid revisiting nodes. - For unweighted shortest paths, BFS is sufficient.

### Week 7: Dynamic Programming (DP)

**Topics:** - Introduction to DP: memoization & tabulation - Classic problems: Fibonacci, Knapsack, LIS - Grid DP, state compression

**Weekly Tips:** - Identify overlapping subproblems and optimal substructure. - Start with recursive solution, then memoize or tabulate. - Practice simple to complex DP to build intuition.

### Week 8: Advanced Graph Algorithms

**Topics:** - Minimum Spanning Trees: Prim, Kruskal - Bellman-Ford for negative weights - Floyd-Warshall for all-pairs shortest paths - Strongly Connected Components (Kosaraju, Tarjan)

**Weekly Tips:** - MST: Focus on edge selection and cycle prevention. - Bellman-Ford: Detect negative cycles. - Floyd-Warshall: Use DP-like approach for all-pairs shortest path. - SCC: Identify components and condensation graph.

### Week 9: Greedy & Interval Problems

**Topics:** - Activity Selection Problem - Interval Scheduling - Interval Covering - Fractional Knapsack

**Weekly Tips:** - Always sort intervals by finishing time for scheduling problems. - Greedy works when local optimum leads to global optimum. - Pay attention to edge cases where intervals overlap. - Fractional Knapsack can be solved using sorting by value/weight ratio.

### Week 10: Advanced Dynamic Programming

**Topics:** - DP on Trees - Bitmask DP - Sequence DP with constraints (e.g., subsequences, partitions) - Optimization techniques: prefix sums, cumulative DP

**Weekly Tips:** - DP on trees: use DFS and store DP for subtrees. - Bitmask DP: useful for problems with small n (<=20) subsets. - Sequence DP: carefully define states and transitions. - Optimize using cumulative sums, monotonic queues when possible.

### Week 11: Network Flow & Matching

**Topics:** - Max Flow (Ford-Fulkerson, Edmonds-Karp) - Min Cut - Bipartite Matching (Hungarian Algorithm, Hopcroft-Karp) - Flow-based problem solving

**Weekly Tips:** - Max Flow: Understand residual graph and augmenting paths. - Min Cut: Relates to Max Flow by MFMC theorem. - Bipartite Matching: Use flow or DFS-based approaches. - Practice transforming problems into flow networks.

### Week 12: Geometry & Computational Geometry

**Topics:** - Points, Lines, and Vectors - Distances and Angles - Convex Hull (Graham Scan, Andrew’s Algorithm) - Polygon Area and Intersection - Line Sweep and Geometric Algorithms

**Weekly Tips:** - Use structures/classes for points and vectors for clarity. - Pay attention to precision and rounding errors with floating points. - Start with simple geometry: distances, dot/cross product. - Convex hull is fundamental for many polygon problems. - Line sweep technique is useful for intervals and intersections.

### Week 13: String Algorithms & Advanced Pattern Matching

**Topics:** - Suffix Arrays & LCP arrays - Trie (Prefix Tree) - Z-Algorithm for pattern matching - String Hashing (Rabin-Karp) - Aho-Corasick Algorithm

**Weekly Tips:** - Suffix arrays allow fast substring search and comparison. - Tries are useful for prefix-based problems and autocomplete. - Z-algorithm computes matching prefixes efficiently. - Rolling hash (Rabin-Karp) allows constant-time substring hashing. - Aho-Corasick handles multiple pattern matching efficiently.

### Week 14: Advanced Graph Theory & Shortest Paths

**Topics:** - Dijkstra’s Algorithm with priority queue - Bellman-Ford optimizations - Floyd-Warshall for all-pairs shortest paths - Johnson’s Algorithm for sparse graphs - Shortest path variations: k-shortest paths, negative cycles

**Weekly Tips:** - Use priority queue (min-heap) for efficient Dijkstra. - Bellman-Ford useful for graphs with negative weights. - Floyd-Warshall computes all-pairs shortest paths in dense graphs. - Johnson’s algorithm combines Dijkstra and reweighting for sparse graphs with negative edges. - Practice different variants and modifications of shortest path problems.

### Problem 1: Dijkstra with Priority Queue

**Link:** [CSES Shortest Routes I](https://cses.fi/problemset/task/1671/) **Difficulty:** Intermediate

**C++ Solution with Explanation Comments:**

#include <bits/stdc++.h>  
using namespace std;  
int main(){  
 int n,m; cin>>n>>m;  
 vector<vector<pair<int,int>>> adj(n+1);  
 for(int i=0;i<m;i++){  
 int u,v,w; cin>>u>>v>>w;  
 adj[u].push\_back({v,w});  
 }  
 vector<long long> dist(n+1, LLONG\_MAX);  
 dist[1]=0;  
 priority\_queue<pair<long long,int>, vector<pair<long long,int>>, greater<>> pq;  
 pq.push({0,1});  
 while(!pq.empty()){  
 auto [d,u]=pq.top(); pq.pop();  
 if(d>dist[u]) continue;  
 for(auto [v,w]:adj[u]){  
 if(dist[u]+w<dist[v]){  
 dist[v]=dist[u]+w;  
 pq.push({dist[v],v});  
 }  
 }  
 }  
 for(int i=1;i<=n;i++) cout<<dist[i]<<" ";  
}

**Explanation Comments:** - Priority queue ensures we always expand the closest unvisited node. - Efficient O((n+m) log n) for sparse graphs. - Skip outdated entries where current distance is already larger than stored.

**End of Week 14** - Focus on understanding priority queues in Dijkstra. - Practice shortest path problems on graphs with different edge types. - Study negative cycles detection and graph reweighting techniques.